Table	Team Name
1	Miami University Vertical Takeoff and Landing Aircraft
2	PixelPals
3	Hydro Gravitational Energy Storage System
4	Database Design and Visualization / Visualite
5	Molding
6	mmWave Radar for Search-and-Rescue Operations
7	Security of Machine Learning II
8	Collaborative Flowchart Tool V2
9	Biomimetic Helmet Design (Device Design For Sports)
10	JETCAT Thrust Reversal
11	Load Shed/Rolling Blackout
12	
13	Softball Tournament Planner Team I
14	Automatic Composing Nursing
15	Softball Tournament Planner Team III
16 17	
1 /	Design of a Biochemical Process for Small-Molecule Chemical Production
10	
18	Building an Efficient Composting Structure
19	Energizer: Micro UV Decontamination
20	Computer Vision For Healthcare
21	Proposal Management Chatbot
22	Bowling Anti-Radiation Missile Simulation
23	
24	The Hearts App Ped/Phys Video Come for Attack and Defensive Applysic
	Red/Blue Video Game for Attack and Defensive Analysis
	Crop Poller
27	Crop Roller Designing a Low Cost Cluton Sensor Hillizing Antomore and
28	Designing a Low-Cost Gluten Sensor Utilizing Aptamers and
20	Gold Nanoparticles
30	AVID Customer Matching System HBC Remote
31	
	Developing Transport Phenomena Laboratory Pattern Powered Refrigeration Unit (RRU) (KEC2)
33	Battery Powered Refrigeration Unit (BRU) (KEG2) Harnessing Artificial Intelligence and Machine Learning for
34	
25	License Plate Recognition
35	Security of Machine Learning I
36	CyberSecurity CTF
37	Alcoholysis of PET in Nonaqueous Solvents for Polymer
20	Recycling Multi-clot MUD Rose for Injection Molding
38	Multi-slot MUD Base for Injection Molding
39	Metaverse Interaction
40	ElderEase Exosuit
41	Tic-Tac-Co
42	Robotic Dog - Project Buster
43	Solar District Cup

44	Bus Scheduling Mobile Application
45	Car Wash
46	Fischer Backus
47	Separating Methane and Carbon Dioxide from Biogas using PDMS Membranes
48	Graph Your Own Adventure (GYOA)
49	Swarm Robotics
50	Climb Higher
51	Mixed Meta Machine
52	3D-Printed Prosthetic
53	Proposing a New Design for a 3D Printed Hip Implant
54	KEG 1
55	Virtual Twinning to Measure a Circuit and Predict Component Failure
56	Contract Management System
57	Synthesis of Electrochemical Biosensor for Fatigue Analysis via Lactate Detection
58	QuickQuit
59	Unpaper
60	Robotic Swarm Using Artificial Intelligence for Direction
	Finding and Localization
61	Customer Onboarding Experience
62	Pulse Oximeter Construction
63	Pelletizer
64	Purrfect Health
<i>(= 1)</i>	Denormaling The Corrugated Boy
65	Papermaking - The Corrugated Box
66	Virtual Personal Trainer
66 67	Virtual Personal Trainer Formula SAE Powertrain Development
66 67 68	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups
66 67 68 69	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner
66 67 68 69 70	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water
66 67 68 69 70	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch
66 67 68 69 70 71 72	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project
66 67 68 69 70 71 72 73	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization
66 67 68 69 70 71 72 73 74	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car
66 67 68 69 70 71 72 73 74 75	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car Water Jet
66 67 68 69 70 71 72 73 74 75 76	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car Water Jet Autonomous Vehicles using the Robot Operating System
66 67 68 69 70 71 72 73 74 75 76	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car Water Jet Autonomous Vehicles using the Robot Operating System Capstone Management System Team 1
66 67 68 69 70 71 72 73 74 75 76 77	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car Water Jet Autonomous Vehicles using the Robot Operating System Capstone Management System Team 1 Self Driving Car
66 67 68 69 70 71 72 73 74 75 76 77 78	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car Water Jet Autonomous Vehicles using the Robot Operating System Capstone Management System Team 1 Self Driving Car Automated Attendance System
66 67 68 69 70 71 72 73 74 75 76 77 78 79	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car Water Jet Autonomous Vehicles using the Robot Operating System Capstone Management System Team 1 Self Driving Car Automated Attendance System Industry Relations CRM
66 67 68 69 70 71 72 73 74 75 76 77 78 80 81	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car Water Jet Autonomous Vehicles using the Robot Operating System Capstone Management System Team 1 Self Driving Car Automated Attendance System Industry Relations CRM Neuro App
66 67 68 69 70 71 72 73 74 75 76 77 78 80 81 82	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car Water Jet Autonomous Vehicles using the Robot Operating System Capstone Management System Team 1 Self Driving Car Automated Attendance System Industry Relations CRM Neuro App NES Emulator
66 67 68 69 70 71 72 73 74 75 76 77 78 80 81	Virtual Personal Trainer Formula SAE Powertrain Development IntelliGroups OwlByte Virtual Pet Planner Adsorption Process Using Activated Biomass to Remove Manganese from Potable Water Afton Chemical Clutch Planter/ No Till Drill Project UC Health Emergency Department Optimization Miami University's Chem-E-Car Water Jet Autonomous Vehicles using the Robot Operating System Capstone Management System Team 1 Self Driving Car Automated Attendance System Industry Relations CRM Neuro App

MME

CPB

CSE

ECE

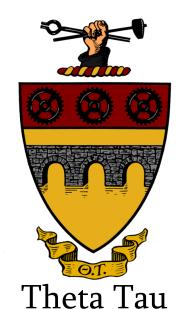
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